

# **Dual M.2 Accelerator Module Hardware Specification**

V0.1

## Open Compute Project - Dual M.2 Accelerator Module Hardware Specification

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# 1 Scope

This document describes the specification of a Dual M.2 accelerator module derived from the standard M.2 form factor, which provides a larger floor plan and power envelope to enable novel ASIC -based accelerator applications.

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## 3 Overview

The high-level hardware specifications are listed below:

**Table 1. Hardware Specification Table** 

Outline	46 x 110mm				
Pin Definition	Two sets of M.2 22110 Socket 3 key M Pin Definition with some NC pins redefined.				
Board Thickness	0.8mm +- 10%				
Board Layer Count	Maximum 12 layers				
Component Height	2.0mm on top layer and 1.5mm on bottom layer <sup>1</sup>				
Power	20W sustained RMS power, refer to chapter 5.2 for more details.				
PCIE <sup>2</sup>	Gen4 or Gen3, 8 lanes, refer to chapter 5.4 for more details				

- 1. Height keepout just defines SMT component. It does not include the heat sink or thermal materials.
- 2. PCIE shall be compliant to PCI Express Base Specification Revision 3.1/4.0

The module includes one ASIC, 4x LPDDR4x DRAMs and supporting circuits. All of the circuitry shall be within the dual M.2 standard form factor and should not require any auxiliary circuit on the system mother board to meet the interface spec.

A recommended placement of Dual M.2 module is drawn in Figure 1. The ASIC shall be placed on the top side of the board and ideally is expected to be sitting in the center area of the board for optimal thermal performance. The supplier can adjust the placement based on the tradeoff between thermal and routing study.

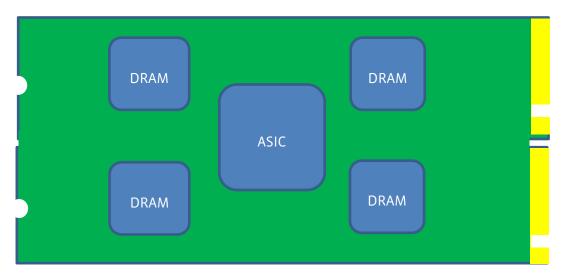


Figure 1: Dual M.2 Module outline

A module shall include, but not limited to the following components:

- 1. ASIC to run the workload
- 2. LPDDR4x Chips
- 3. Power Circuits
- 4. SMBus EEPROM or on-chip memory to save FRU information, 8bit SMBus address 0xA6 as defined in NVMe Specification.
- 5. Storage for boot firmware if needed but NAND Flash is not allowed.

# 4 System Block Diagram

Dual M.2 Accelerator modules will be plugged in to the Glacier point Version 2 (GPv2) card, which is a PCIE extension card defined in the Yosemite V2 (YV2) system. For more details of GPv2 card you can refer to GPv2 hardware specification document.

Glacier Point V2 card is the carrier card inserted in the Yosemite V2 sled. It is plugged in slot 1 and 3 in the below graph. It pairs with the twin lake server to form a subsystem. Slot1 and slot2 are a pair and slot 3 and slot 4 are another pair.

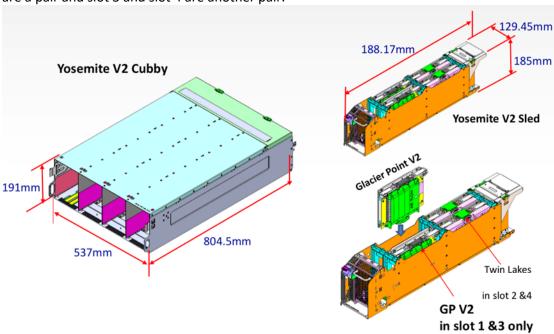


Figure 2: Yosemite V2 and Glacier point V2 system drawing

Previously we have designed a Glacier Point V1 card which is a M.2 carrier card in YV2 system which supports 6x M.2 cards. In GPv2 design, we have made several changes to better support accelerator workload. The major changes are:

- Each GPv2 card could support 6x dual-M.2 cards
- Added a PCIe Switch to fanout PCIe lanes
- Included a bridge micro-controller to manage the sideband of each M.2 card

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- Included a CPLD to mux UART and JTAG of each module to the debug interface
- Added a power switch to each M.2 card to allow control software to perform complete power cycle of each M.2 cards independently when system is in powered on

PCle block diagram is listed in Figure 3. There is a Microsemi PM8535 PCle switch to fanout 16 PCle lanes from USP to support 6 PCle Gen3 x8 links at DSP.

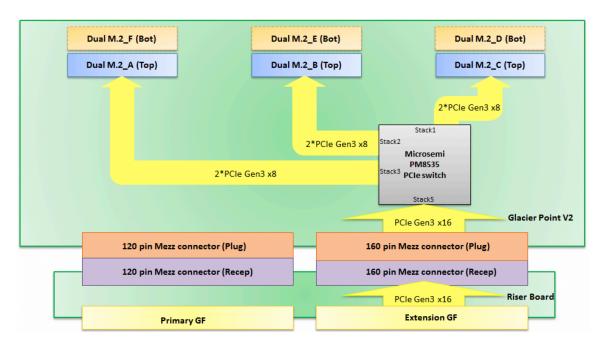


Figure 3. PCle Block Diagram on GPv2

The block diagram of SMBus topology in GPv2 system is listed below. M.2\_A through L represent the M.2 connectors. GPv2 card support both M.2 and Dual M.2 modules. Each Dual M.2 module will occupy two adjacent M.2 connectors. In this diagram, SNOW FLAKE represents the bridge IC, which is a micro-controller that manages the GPv2 board. INA231 is the voltage and current monitor. PCA9846PW is the SMBus Mux.

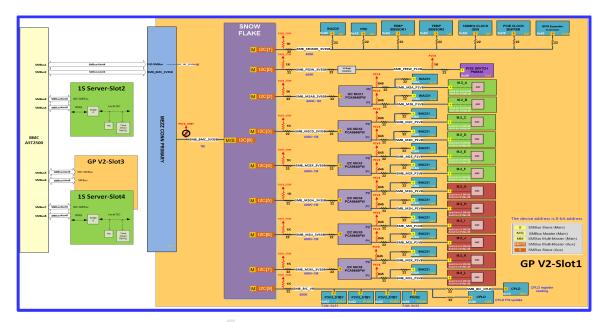


Figure 4: Typical GPv2 SMBus topology

Yosemite V2 design has defined the debug port on the front panel to ensure the accessibility. Meanwhile the remote debug capability is a feature that is useful in the fleet so that we can dump the error log once the system fails without the need to have the operator to be personally there.

In GPv2 we design with common clock topology. The host CPU will provide the clock to all the Dual M.2 modules through a clock buffer on GPv2 card. PM8535 PCIE switch provide PCIE clock to all M.2 connectors. The dual M.2 module will only use the clock from the primary side.

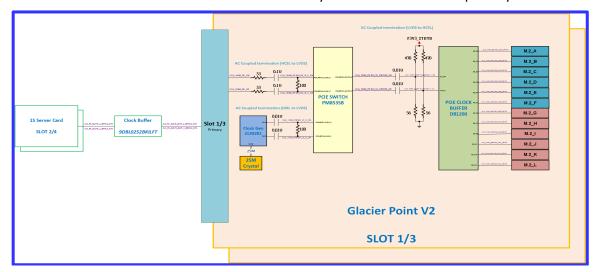


Figure 5: PCIE clock tree

JTAG and UART interfaces are muxed to the system through a CPLD chip. UART port will finally connect both BMC chip and front end debug port on YV2 baseboard. The block diagram is listed below:

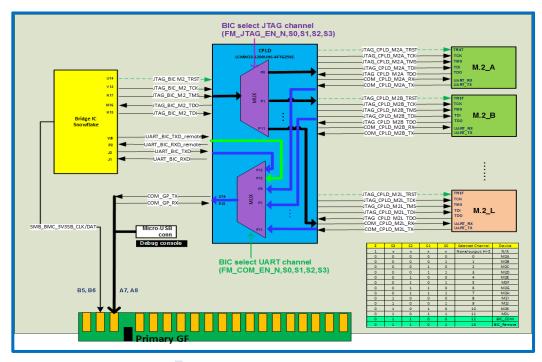


Figure 6: JTAG and UART block on GPv2 board.

# 5 Module Hardware Specification

### 5.1 Pin Definition

The Dual M.2 form factor is the combination of two sets of M.2 22110 Socket 3 key M Pin Definition. The main slot has the full set of connections and the 2<sup>nd</sup> slot just provides additional power, ground, and PCIe connections. Each Dual M.2 card shall support 8 PCIE lanes.

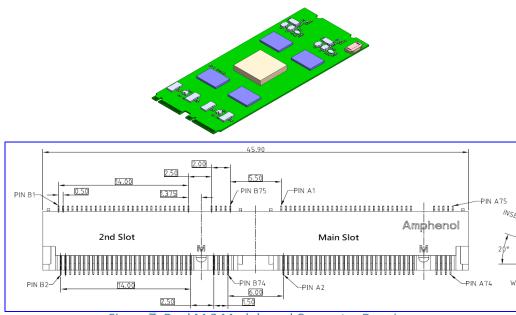


Figure 7: Dual M.2 Module and Connector Drawing

				Dual M.2				
	Main S	lot (SlotA)				2nd Slo	t (SlotB)	
Signal	Pin	Pin	Signal		Signal	Pin	Pin	Signal
3.3V	A2	A1	GND		3.3V	B2	B1	GND
3.3V	A4	А3	GND		3.3V	B4	В3	GND
PWRDIS	A6	A5	PETn3		NC	B6	B5	PETn7
PLN#	A8	A7	PETp3		NC	B8	B7	PETp7
LED_1#(0)	A10	A9	GND		NC	B10	B9	GND
3.3V	A12	A11	PERn3		3.3V	B12	B11	PERn7
3.3V	A14	A13	PERp3		3.3V	B14	B13	PERp7
3.3V	A16	A15	GND		3.3V	B16	B15	GND
3.3V	A18	A17	PETn2		3.3V	B18	B17	PETn6
TRST	A20	A19	PETp2		NC	B20	B19	PETp6
VIO_1V8	A22	A21	GND		GND	B22	B21	GND
TDI	A24	A23	PERn2		NC	B24	B23	PERn6
TDO	A26	A25	PERp2		NC	B26	B25	PERp6
TCK	A28	A27	GND		GND	B28	B27	GND
PLA_S3#	A30	A29	PETn1		NC	B30	B29	PETn5
GND	A32	A31	PETp1		NC	B32	B31	PETp5
USB_D+	A34	A33	GND		NC	B34	B33	GND
USB_D-	A36	A35	PERn1		NC	B36	B35	PERn5
GND	A38	A37	PERp1		NC	B38	B37	PERp5
SMB CLK (I/O)(0/1.8V)	A40	A39	GND		NC	B40	B39	GND
SMB DATA (I/O)(0/1.8V)	A42	A41	PETn0		NC	B42	B41	PETn4
ALERT# (O)(0/1.8V)	A44	A43	PETp0		NC	B44	B43	PETp4
Reserved_UART_Rx	A46	A45	GND		NC	B46	B45	GND
Reserved_UART_Tx	A48	A47	PERn0		NC	B48	B47	PERn4
PERST# (I)(0/3.3V)	A50	A49	PERp0		NC	B50	B49	PERp4
CLKREQ# (I/O)(0/3.3V)	A52	A51	GND		NC	B52	B51	GND
PEWAKE#(I/O)(0/3.3V)	A54	A53	REFCLKn		NC	B54	B53	NC
Reserved for MFG DATA	A56	A55	REFCLKp		NC	B56	B55	NC
Reserved for MFG CLOCK	A58	A57	GND		NC	B58	B57	GND
ADD IN CARD KEY M			ADD IN CARD KEY M		ADD IN CARD KEY M			ADD IN CARD KEY M
ADD IN CARD KEY M			ADD IN CARD KEY M		ADD IN CARD KEY M			ADD IN CARD KEY M
ADD IN CARD KEY M			ADD IN CARD KEY M		ADD IN CARD KEY M			ADD IN CARD KEY M
ADD IN CARD KEY M			ADD IN CARD KEY M		ADD IN CARD KEY M			ADD IN CARD KEY M
NC	A68	A67	TMS		NC	B68	B67	NC
3.3V	A70	A69	NC		3.3V	B70	B69	NC
3.3V	A72	A71	GND		3.3V	B72	B71	GND
3.3V	A74	A73	VIO_CFG_GND		3.3V	B74	B73	GND
		A75	GND				B75	GND

Figure 8: Dual M.2 Module Pinout Table

This pinout table and I/O direction is defined from the perspective of the module (not the baseboard perspective). Pin definition is compatible to PCI-SIG M.2 specification though we have re-defined several NC pins mainly for debug purposes. These features are expected to improve the debug capability once hardware is deployed in large scale data center environment.

Table 2. M.2 Module Pinout description

Interfa ce	Signal Name	1/0	Description	Voltage	Requirement
Power Ground	3.3V(18 pins) GND(31 pins)	I	3.3V running power source Ground	3.3V 0V	Required Required
	VIO_1V8	I	Reserved 1.8V running power source for future PCI-SIG standard.	1.8V	NC in module the platform will leave leave this pin open.
	PETp0/PETn0	0	PCIe TX/RX Differential		Required
PCle	PETp1/PETn1	О	signals defined by the PCIe		

			2.4/4.0 000 - 15:		
	PETp2/PETn2	0	3.1/4.0 specification. The Tx/Rx are defined on		
	PETp3/PETn3	0	module perspective. PCIe Tx		
	PETp4/PETn4	0	net shall connect to the Rx on the host side.		
	PETp5/PETn5	0			
	PETp6/PETn6	0			
	PETp7/PETn7	0			
	PERp0/PERn0	I			
	PERp1/PERn1	I			
	PERp2/PERn2	I			
	PERp3/PERn3	I			
	PERp4/PERn4	I			
	PERp5/PERn5	I			
	PERp6/PERn6	1			
	PERp7/PERn7	I			
	REFCLKp/REF CLKn	I	PCIe Reference Clock signals (100 MHz) defined by the PCIe 3.1/4.0 specification		Required
	PERST#	I	PE-Reset is a functional reset to the card as defined by the PCI Express CEM Rev3.0	3.3V	Required
	CLKREQ#	1/0	Clock Request is a reference clock request signal as defined by the PCIe Mini CEM specification; Open Drain with pull up on Platform; Active Low; Also used by L1 PM Substates.	3.3V	Optional. The platform will leave leave this pin open.
	PEWAKE#	1/0	Vendor do not need to support this feature	3.3V	Optional. The platform will leave this pin open.
Specific Signals	Reserved for MFG DATA		Manufacturing Data line.		Optional. The platform will
	Reserved for MFG CLOCK		Manufacturing Clock line.		leave this pin open.
	LED1# (O)	О	LED pin	3.3V	Optional. The platform will

					leave this pin open.
	ALERT#	О	Alert notification to master; Open Drain with pull up on Platform; Active Low.	1.8V	Required. Refer to Sec 5.3 for more details.
	SMB_CLK	I/O	SMBus clock; Open Drain with pull up on Platform, no pull up needed on module. module is slave only.	1.8V	Required
	SMB_DATA	I/O	SMBus data; Open Drain with pull up on platform, no pull up needed on module. module is slave only.	1.8V	Required
USB	USB_D+	I/O	USB 2.0 bus reserved for future application.	N/A	NC in module, The platform will leave this pin open.
	USB_D-	I/O	USB 2.0 bus reserved for future application, not required here.	N/A	NC in module The platform will leave this pin open.
UART	Reserved_UA RT_RX	I	UART Receiver Pin based on module perspective. It shall connect to the Tx pin on the host side.	1.8V	Required. Please refer section 5.3 for details.
	Reserved_UA RT_TX	0	UART Transmitter Pin based on module perspective. It shall connect to the Rx pin on the host side.	1.8V	Required. Please refer section 5.3 for details.
JTAG	TDI	1	Refer to JTAG Specification	1.8V	Required. Please
	TDO	0	(IEEE 1149.1), Test Access Port and Boundary Scan	1.8V	refer section 5.3 for details.
	TCK	1	Architecture for definition.	1.8V	
	TMS	I	The definition is also based on module perspective.	1.8V	
	TRST	1		1.8V	
Reserv ed New IOs	PWRDIS	I	Reserved for power disable pin. High: disable power on module. This pin shall be NC on module.	3.3V	The platform does not support these features.

PLN#	I	Reserved for Power Loss notification. NC in module.	3.3V
PLA_S3#	0	Reserved for Power loss Assert. NC in module.	3.3V
VIO_CFG_GN D	0	Reserved for IO configure pin. Connected to ground in module.	0V

## 5.2 Power Specification

### 5.2.1 Operating (steady state) Conditions

The M.2 module utilizes a single regulated power rail of 3.3 V provided by the platform. The power requirement is called out as below:

**Table 3. Operation Mode Rating** 

Norminal supply Voltage	3.3V
Supply Voltage Tolerance	+/-5%
ASIC Junction Temperature	7% lower than the lowest throttle temperature, specified at Max TDP operating case (e.g. if the throttle temp is 70C then the
	operating temp would be 65C)

The module shall support Low Performance and Target performance levels with Highest performance mode as an optional level as listed in Table 4. The module will determine the operating TDP mode during power on stage from firmware. This is a static power level, it is not changed during run time through software, and defines the maximum sustained power drawn from the system during normal operation. The module components should be designed to support the highest power level that the module can be used in.

**Table 4. Module TDP table** 

	Low Perf	Target Perf	Highest Perf
Module TDP* power level	15W	20W	25W
Module Absolute Peak Power allowed	25W	30W	35W
(For a 20us load step transient)			
Module Performance	>= 80%	100% of the performance	>= 120%
(assuming DRAM ECC enabled)		target	

\*TDP: Thermal Design Power is the sustained average power that the module dissipates while under continuous heavy workload, 50C local ambient temperature and the ASIC junction temperature defined as above in table 3.

#### 5.2.2 Peak (instantaneous) conditions

Transient/Instantaneous power spikes allowed in operation are defined by the absolute peak power specification. Absolute peak power allowed can vary based on the duration time of the peak power transient load step. Fig.9 represents the curve that defines the peak power vs. load step duration time based on the GPv2 card design and Yosemite V2 platform peak power budget. These are not specified for a power virus condition, but for peak instantaneous power observed while running application workloads.

The peak power here is defined at the 3.3V connector input. The decoupling capacitors and PMIC/VR on the module are expected to suppress transients shorter than 5us to peak power of 40W. If higher transients are expected for these short durations at module input, peak power limiting loop internal to the module should be fast enough to limit the instantaneous peak power to less than 40W.

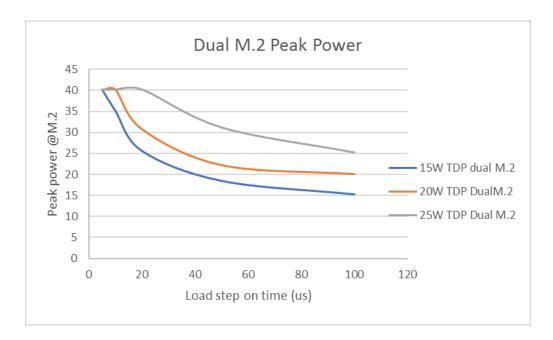


Figure 9: M.2 Peak power specification details across load step

## 5.2.3 Input Capacitance and undervoltage specification

Input capacitance on the 3.3V connectors should be limited to less than 2mF per dual M.2 module. Device UVLO (minimum voltage for M.2 VR to turn on) should be set to greater than 2.8V to ensure power on ramp time meets PCIE ramp spec and does not stress load switch in addition to capacitive inrush current. Power tree to derive the 3.3V from 12V is described in Fig.10. Power sensors used here are capable of sensing only sustained load currents (>100ms sampling after averaging).

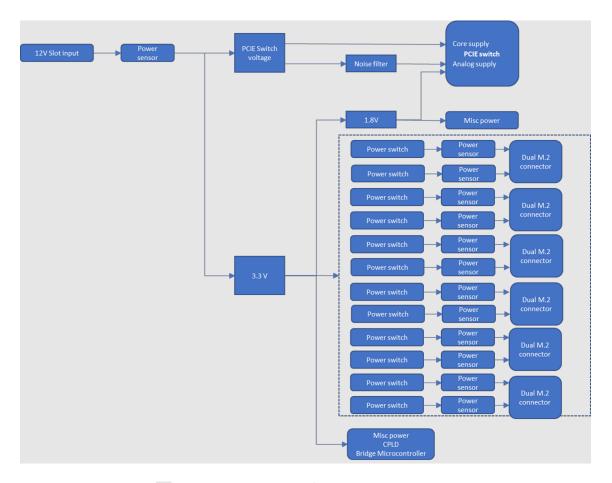


Figure 10: M.2 Power supply configuration on GPv2 carrier card

## 5.3 **IO Description**

#### 5.3.1 ALERT#

This pin shall be used as a hardware interrupt for module failures. The ALERT# pin is connected individually to the Bridge IC as shown in Fig. 4. The ALERT# pin shall be triggered by the module health byte as defined in the sideband memory map. The ALERT# pin shall be released after this module health byte is read.

#### **5.3.2** SMBus

Module shall be SMBus/I2C slave to the host with 7-bit address 0x6A which is defined based on NVMe-MI base command interface. FRU information shall be stored in either an EEPROM on the PCB or in on-chip memory in the ASIC, at 8 bit address 0xA6. This bus shall support 100kHz, 400kHz and 1MHz mode. By default, it shall run at highest speed among the three frequencies mentioned here.

#### 5.3.3 **UART**

The UART is defined at 1.8V signaling levels. The baud rate is 57600. The module shall buffer this interface to avoid current leakage if the ASIC is not powered.

#### 5.3.4 JTAG

The JTAG interface should be compliant to IEEE standard 1149.1. The module shall buffer this interface to avoid current leakage if the ASIC is not powered.

## 5.4 PCIe Description

#### 5.4.1 Physical interface

The module PCIe physical interface shall be compliant to PCI-SIG CEM specification 3.0. If the module is capable to run at Gen4 speed, the interface shall be compliant to PCI-SIG CEM Specification 4.0.

Module shall support x8 bifurcation as the default configuration. The module shall also support fail down mode to x4 bifurcation (lane0-3) automatically once plug in to the system where only the primary connector PCIe lanes are connected.

The module shall support PCIe lane and polarity reversal. For the x8 case, the module should support 0->7 to 7->0 lane reversal. In the fail down (x4) mode, lane reversal is from 0->3 to 3->0.

The module PCIe interface shall support common clock topology with Spread Spectrum Clocking (SSC). SSC's modulation frequency is from 30-33KHz with -0.5%-0% deviation. Separate Reference clock topology support is a preferred but not required.

PCIe routing maximum link loss, including the PCB trace plus the package loss on the module, shall be less than 5dB at 4GHz for PCIe Gen3. The link loss for PCIe Gen4 is defined to be less than 7.5dB at 8GHz. The module trace impedance shall be 85ohm differential impedance for the PCIe lanes.

#### 5.4.2 PCle power-up timing

The power-up timing of PCIe functions shall follow CEM specification 3.0. Here is the drawing copying from CEM spec:

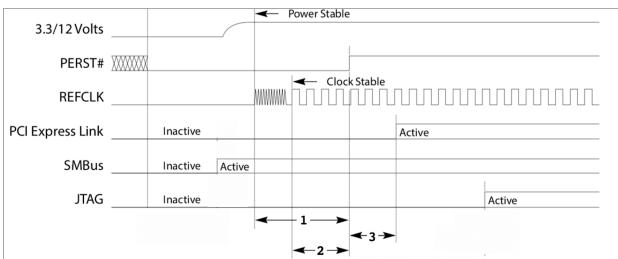


Figure 11: PCIE Power Up Timing

### **Timing Notes:**

- 1- Minimum time from power rails within specified tolerance to PERST# inactive (T<sub>PVPERL</sub>): T<sub>PVPERL</sub> >100ms
- 2- Minimum clock valid to PERST# inactive(T<sub>PERST-CLK</sub>): T<sub>PERST-CLK</sub> > 100us
- 3- Minimum PERST# inactive to PCI Express link out of electrical idle:
  - a. Link LTSSM must enter detect state within 20ms from PERST# being deasserted. This implies that any PHY settings need to be applied to the PCIe PHY before this timing requirement has been exceeded. Caution should be taken here as this may require a boot ROM to execute and/or information to be loaded from SPI flash as well as a reset sequence applied to the logic for it to take effect.
  - b. Link must be ready for configuration request within 120ms from PERST# being deasserted.

#### 5.4.3 Reset mechanisms

The module shall support the following reset mechanisms when the module POWER GOOD indicates that power supplies are stable on the module.

#### Out of band:

Cold Reset: Signalled by module power good transition from low to high, followed by PCle PERST# transition from low to high (refer Fig. 11). This is the cold boot scenario for the module and a fundamental reset as defined by the PCle specification.

Warm Reset: This is signaled by a transition in PERST# without any transition on module POWER GOOD. This should be interpreted by the ASIC as a warm reset where the PCIe link stays active.

#### In Band:

PCle hot reset: This is signaled in band as per the PCle specification and the device should respond as per the specification.

PCIe Function level reset: This reset is also signaled in-band and the device should meet all the requirements of the PCIe specification.

In addition, as this module will be used in lights out datacenters, we need to have the ability to monitor device health and status using the out of band interface. To meet this requirement the module needs to be able to respond to reads over the OOB interface (SMBUS) while any of the resets are asserted (except COLD RESET). The accelerator shall respond in one of two ways:

- 1. Return valid data
- 2. Signal device not ready over the SMBus/i2c protocol

## **5.4.4** PCle Configuration

The module shall be configured as a PCIe end-point device. Additionally, the ASIC PCIe controller shall support the following:

- A Max Payload Size (MPS) of >= 256 Bytes
- 2. A Max Read Request Size (MRRS) of >= 512 Bytes

- 3. At least one BAR shall be pre-fetchable, 64bits, and configurable to be at least 1GB in size
- 4. The DMA engine shall be capable of saturating at least the PCIe gen4 x4 connection and ideally the full x8 PCIe BW.
- The DMA engine shall be capable of mapping to all of host memory and the ability to map the majority of the memory on the module with certain memory regions mapped out due to security concerns.
- 6. The DMA engine shall support a link latency of >= 1us.
- 7. The DMA engine shall support the ability for software/firmware to enable/disable PCIe MSI/MSI-X interrupts per DMA command and programmatically map the interrupts to either the host or internal CPU cores so that it is possible to chain multiple PCIe commands together.

## 5.5 FRU specification

The supplier's FRU is stored in an EEPROM or memory area within the ASIC that can be accessed from sideband SMBus line at 8bit address 0xA6. The FRU format should follow *IPMI Platform Management FRU Information Storage Definition 1.0, Version 1.2.* The FRU template is listed in table 5. The supplier should provide the detailed FRU information for review before the module builds.

**Table 5. FRU Required Fields** 

Organization	String
Board Info Area	
Language Code	19h (English)
Board Mfg Date	[Generate build time]
Board Mfg	Defined by vendor
Board Product	Defined by vendor
Board Serial Number	Defined by vendor
Board Part Number	Defined by vendor
Fru File ID	Defined by vendor
Custom Field 2	Accelerator Dual M.2
Product Info Area	
Language Code	19h (English)
Product Manufacturer	Defined by vendor
Product Name	Defined by vendor
Part/Model Number	Defined by vendor
Product Version	Defined by vendor

Product Serial Number	Defined by vendor
Product Asset Tag	Defined by vendor
Product Build	EVT (or DVT, PVT)

# 6 PCB Specification

To maintain the mechanical compliance between the dual M.2 module and connector, a special connector and tighter control on PCB edge finger area is required. Here we disclose the drawing of PCB edge finger area in Fig.12. The full drawing of PCB, landing footprint and connector will be disclosed in future revision. A side is the primary side and B side is the secondary side.

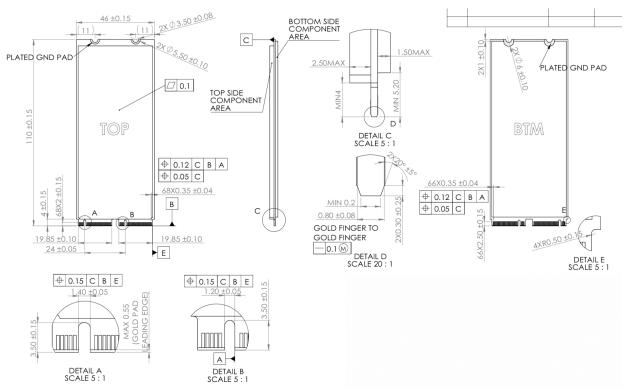


Figure 12: Dual M.2 module PCB Drawing

For the tolerance that has not been called out here, Refer to PCI Express M.2 Specification Revision 1.1 for the PCB outline mechanical specification.

HDI type PCB manufacturing is expected here to support high density routing and high density BGA package of ASICs. Vendor could use OSP or ENIG surface finishing on PCB except the golden finger area.

The supplier shall follow below requirement for PCB soldermask color:

**EVT-Red** 

**DVT-Yellow** 

PVT/MP-Blue

## 7 Thermal and Heatsink

## 7.1 Thermal Design Guidelines

To improve thermal efficiency, the module shall be fully enclosed by a metal case with a module-level heat sink on the ASIC side. Heat sink dimensions and the associated thermal design requirements need to comply with platform that takes the module. Both the module and the heat sink solution for the module shall be provided by the module supplier. The first platform to use the Dual M.2 accelerator module is Glacier Point V2 (GPV2) carrier card in Yosemite V2 platform (YV2). The information below is intended to serve as a reference for this initial use case only.

## 7.2 Integrated Heat Sink Requirements for Dual M.2 in GPV2

This section specifies the dimensions for the integrated heat sink solution for the dual M.2. A reference design is shown in Figure. 13. The supplier is encouraged to use their own module design which meets the mechanical dimension requirements. The latch actuation must be 2.0±0.22 kfg when the latch is fully pressed with 2.5mm travel distance.

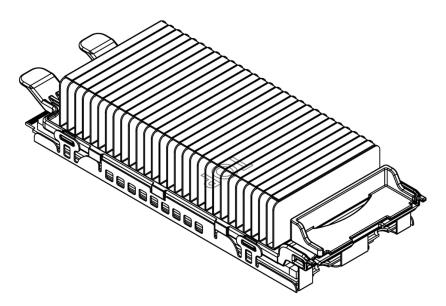


Figure. 13 Reference Design for Dual M.2 Integrated Heatsink

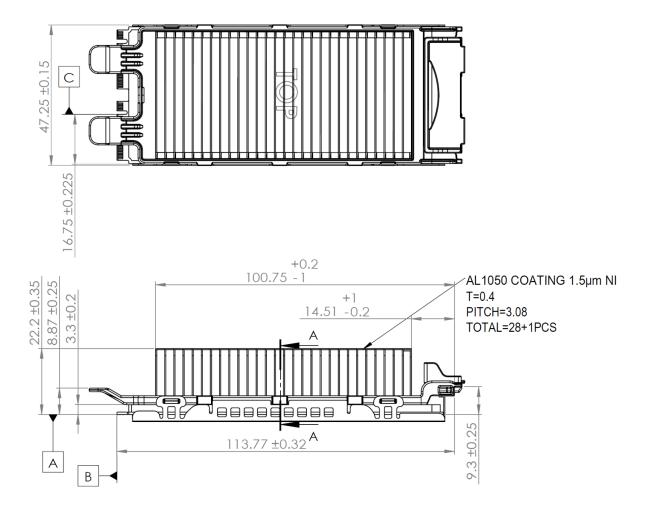
The heat sink's dimensional requirements for dual M.2 accelerator module are listed as below:

- Nominal height from PCB top surface to heat sink top is 21.4mm, which consists of height
  of heat sink, TIM (thermal interface material) and SMT components on top side.
- Nominal height from PCB bottom surface to bottom case is 2.4mm, which consists of thickness the metal case, TIM and SMT components on bottom side (if any).

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- To provide easy access to connector side and platform integration, the heat sink base of the module shall be die-cast and follow the requirements on the latch design.
- Maximum width of the integrated heatsink shall be kept within 47.4mm for a dual M.2 module.

The heatsink should follow below tolerance requirements to allow easy installation into the chassis as shown in Figure. 14.



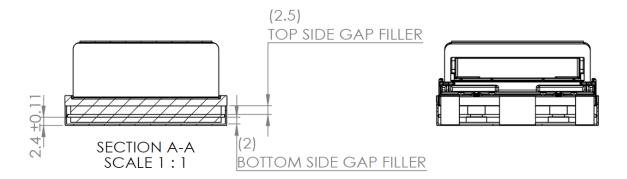


Figure. 14 Dual M.2 Integrated Heatsink Dimensions

## 7.3 Thermal Requirements for Dual M.2 Acceleration Module

The module shall meet the thermal requirement that is defined by the platform. The module shall meet the thermal requirement that as defined by the platform. Specific requirements such as airflow and approach air temperature will be platform specific.

All the temperature values reported by module shall hold at least  $\pm 2^{\circ}$ C accuracy.  $\pm 1^{\circ}$ C accuracy is recommended. The ASIC's module-to-module temperature reporting variation shall be  $\pm 2^{\circ}$ C with  $\pm 1^{\circ}$ C recommended. Two different modules shall not report temperature greater than  $4^{\circ}$ C apart under the same environmental conditions, slot location, and workload.

# 8 Quality and Reliability

Module and ASIC are expected to demonstrate RDT, Compliance, Robustness, Environmental specifications, and Component qualification. A mix of industry product quality standards (JESD, ASTM, EIA, ISTA etc.) along with specific product needs that go above and beyond industry standards are required to be completed and demonstrated as part of product quality reliability, and performance.

### 8.1 RDT

#### 8.1.1 Quality RDT

Hardware component validation, firmware functionality check, as well as product reliability are the key aspects of Reliability Demonstration Test (RDT). The module is expected to demonstrate MTBF (Mean Time Between Failure) of minimum 2.5 million hours in order to assess product early-life quality and potential failure modes. The supplier shall provide the calculated as well as demonstrated MTBF estimates to include sample size, allowable functional failures (1), stress profile (per JESD218A, JESD219A workloads and temperature conditions) at 60%, and 90% confidence level Weibull modeling accordingly. In-lieu of calculated MTBF availability,

component and module level FIT rates are acceptable as well. Planned and Un-planned power loss scenarios are to be accounted as part of MTBF demonstration.

#### 8.1.2 Performance RDT

Module should run work load that can stress the ASIC, DRAM, and PCIE interface. Module vendor would be required to provide the work load for this purpose. Associated test conditions, performance criteria, and duration for this test are TBD.

## 8.1.3 Environmental, and Compliance Specifications

Environmental, compliance specifications, and product robustness requirements are listed below so as to ensure that the module/FRU (with Integrated Heat Sink) level requirements are met, and the product functions as expected with no allowable failures post testing.

Table 6. Q&R testing requirement

Module Stress Test	Test Criteria	Standards (As applicable)	Sample Size
Operational Vibration	2.17 G <sub>rms</sub> , 5-700-5 Hz, all three axes	EIA-364-28	22
Non- Operational Vibration	3.13 G <sub>rms</sub> , 5-1500-5 Hz, all three axes	EIA-364-28	22
Non- Operational Shock	1250G, 0.5ms, 6 drops, all three axes	EIA-364-27	22
Insertion	300 cycles (plating and power on check every 50 cycles)	EIA-364-09	5
EMC Emission and Immunity		CISPR 22/24, EN55022:2010 +AC:2011, ENTT032:2012 +AC:2013, EN55024:2010 EN 6100-3-2:2014 EN 6100-3-3: 2013 Class B	6
Electrostatic Discharge	± 4kV Contact Discharge ± 8kV Air Discharge	EN55024:2010	6

Module FRU Stress Test (with HIS)	Test Criteria	Standards (Applicable)	Sample Size
Operational Vibration	0.5 G <sub>rms</sub> , 5-500-5 Hz, all three axes	EIA 364-28	22
Non- Operational Vibration	1.5 G <sub>rms</sub> , 5-500-5 Hz, all three axes	EIA 364-28	22
Operational Shock	6G, 0.5ms, 6 drops, all three axes	EIA 364-27	22
Non- Operational Shock	70G, 0.5ms, 6 drops, all three axes	MIL-510	22
Package Vibration	1.146 G <sub>rms</sub> , 2-200-2 Hz, all three axes	ISTA 3E 06-06	10 per tray, 4 trays
Package Drop	8-inch drop	ISTA 3E 06-06	10 per tray, 4 trays
Package Compression	Maximum compression loading on a bulk pack	ASTM D 642-94	1
Thermal Shock	-40°C to 85°C, 500 cycles	EIA 364-32	22
(Non- Operational)	(1 Cycle = 5°C to -40°C at ramp 5°C/min, dwell at -40°C for 30 min, -40°C to 85°C at 5°C/min ramp, dwell at 85°C for 30 min, and ramp down to 5°C)		
High Temperature Humidity (Operational)	50°C (local ambient temperature at the module), 90% RH, 500 hours	EIA 364-31	22
Temperature/V oltage Characterizatio n (Operational)	5°C to 50°C (local ambient temperature at the module), Vcc ±x% (per spec), 500 hours		22
Operational Altitude	0 0 ft to 10000 ft		12
Non- Operational Altitude	0 ft to 30000 ft		12

Power Cycle (AC, DC, Reset)	500 cycles each	22

**Note**: The preference is to make use of at least 3 units from the sample size listed above to be subjected to waterfall model reliability testing (using select few tests from above). Test sequence for this implementation is TBD

## 8.2 Compliance

#### **North America**

- FCC: Verification tests only per FCC Part 15 standard. No FCC certification is needed
- UL: RU mark is preferred

#### EU

- **CE mark**: Add CE mark on the accelerator module
- **EMC Directive**: 2014/30/EU- Test partially as applicable
- ROHS Directive: 2011/65/EU
- WEEE mark: WEEE mark on the accelerator module

#### **APAC**

• No specific certification is needed

## 9 Prescribed Materials

## 9.1 Disallowed Components

The following components shall not be used in the design of PCB board:

- Components disallowed by the European Union's Restriction of Hazardous Substances Directive RoHS 2 Directive (2011/65/EU)
- Trimmers and/or potentiometers
- Dip switches

## 9.2 Capacitors and Inductors

The following limitations apply to the use of capacitors:

- Only aluminum organic polymer capacitors made by high-quality manufacturers are used;
   they must be rated 105°C.
- All capacitors have a predicted life of at least 50,000 hours at 45°C inlet air temperature, under the worst conditions.
- Tantalum capacitors using manganese dioxide cathodes are forbidden.

- SMT ceramic capacitors with case size > 1206 are forbidden (size 1206 are still allowed when
  installed far from the PCB edge and with a correct orientation that minimizes the risk of
  cracking).
- Ceramic material for SMT capacitors must be X5R or better (COG or NPO type are used in critical portions of the design). Only SMT inductors may be used. The use of through-hole inductors is disallowed.

## 9.3 Component De-rating

For inductors, capacitors, and FETs, de-rating analysis is based on at least 20% de-rating.

# 10 Labels and Markings

This specification describes label requirements for Dual M.2 accelerators.

## 10.1 Data required

- Manufacturer name
- Country of Origin
- Date code of manufacture, includes year & work week
- Product number = same number used to order product from supplier
- Serial number: unique to each product
- Firmware revision
- Hardware revision
- Capacity of card (GB) TBD: total data space (system + user), total user space, or user space less OP. (This request is for storage product only)
- PCB Vendor name

We might need to apply TIM (gap pad) material on top of high heat dissipating components such as ASIC, NAND flash and controller on either side of the card. Any standard product labels applied on those parts will be obscured by the TIM, so the supplier should install additional labels that contain the Serial Number and the Product Number (same PN used for ordering and stored in the SMART data table. The additional labels can use 2D barcodes to save space. 2D bar codes should have human readable text placed in the margin. 2D barcodes should not have any spaces, but dashes are acceptable.

In another case we may have integrated heat sink that encloses module. In this case the label should be attached on bottom of integrated heat sink.

#### 10.2 Data format

- Human-readable. Font size: 10 or larger. Some data on 2D labels can be size 6
- Barcode. 1D and 2D acceptable. Minimum feature (line width): 10 mils
- Electronically readable, e.g. SMART data table
- Example readers: Motorola/Zebra readers
  - Motorola CS4070
  - Motorola Symbol DS3578-SR
  - Zebra DS3678-DP

Table 7. Label Requirements

	. Laber Requirements		
	Spec		
Data	Human Readable	Barcode	Electronic
Product name	X	Х	Х
Capacity ()			
Serial Number (Human Readable)	Х		Х
Serial Number (Barcode)		Х	
Sub-assembly No. (Human Readable)			
Sub-assembly number (Barcode)		Х	
PCBA Number			
LBA			
Country of Manufacture	X		
Model String	X	Highly Wanted	Х
Warranty Disclaimer			
WWN Worldwide Name (human Readable)			
WWN Worldwide Name (Barcode)			
Firmware Version	X		Х
Canadian String			
Manufacturer Name	х	Х	Х
PCB Vendor		Х	Х
Date code		Х	Х
PSID Human readable			
PSID Barcode			
Production Date Code	X		Х

# **10.3 Agency Compliance Marks**

Module supplier should ensure its products comply with all applicable certificate(s) or verification among the following requirements.

## **EMC/Safety**

- NRTL component level certification
- CE mark based on Directive 2014/35/EC and 2014/30/EU
- FCC verification

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- VCCI
- Korea KCC certification
- Taiwan BSMI

## **Environment regulations**

- ROHS Must be free from hazardous substances prohibited by the RoHS Directives of the EU (European Union)
- China RoHS
- Taiwan RoHS
- WEEE mark
- Halogen Free

# 11 Revision History

Ver	Description	Author	Date
0.1	Internal submission	Facebook	02-25-2019